### Parsing Push-Down-Automata (PDA)

#### Laura Kallmeyer

Heinrich-Heine-Universität Düsseldorf

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Gainvie fainer HEINRICH HEINE UNIVERSITÄT DÜSSELDORF

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# PDA: Intuition (1)

A push-down automaton (Hopcroft and Ullman, 1979, 1994) is a FSA with an additional stack.

The moves of the automaton depend on

- the current state
- the next input symbol
- the topmost stack symbol

Each move consists of

- changing state
- popping the topmost symbol from the stack
- pushing a new sequence of symbols on the stack

# PDA: Intuition (2)

#### Example

Automaton that

- starts with  $q_0$  and stack #
- in *q*<sub>0</sub>: pushes *A* on the stack for an input symbol *a*
- in *q*<sub>0</sub>: pushes *B* on the stack for an input symbol *b*
- in *q*<sub>0</sub>: leaves stack unchanged and switches to *q*<sub>1</sub> for an input symbol *c*
- in  $q_1$ : pops an A from the stack for input symbol a
- in  $q_1$ : pops a *B* from the stack for input symbol *b*
- in  $q_1$ : moves to  $q_F$  if the top of the stack is #
- accepts all words that allow to end up in *q<sub>F</sub>*

Which (string) language does this automaton accept?

In general, PDAs are non-deterministic, since a given state, input symbol and topmost stack symbol can allow for more than one move.

In contrast to FSA, the deterministic version of the automaton is not equivalent to the non-deterministic one: There are languages that are accepted by a non-deterministic PDA but not by any deterministic PDA.

CFLs are the languages accepted by (non-deterministic) PDAs.

# PDA: Definition (1)

#### Push-down automaton

A **push-down automaton** (PDA) *M* is a tuple  $\langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle$ :

- *Q* is a finite set of states
- $\blacksquare$   $\Sigma$  is a finite set, the input alphabet
- $\blacksquare$   $\Gamma$  is a finite set, the stack alphabet
- $q_0 \in Q$  is the initial state
- $Z_0 \in \Gamma$  is the initial stack symbol
- $F \subseteq Q$  is the set of final states
- $\delta: Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \to \mathcal{P}_{fin}(Q \times \Gamma^*)$  is the transition function  $(\mathcal{P}_{fin}(X) \text{ is the set of finite subsets of } X)$

Equivalently, one can even define  $\delta$  as  $\delta: Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma^* \to \mathcal{P}_{fin}(Q \times \Gamma^*).$  An **instantaneous description** of a PDA is a triple  $(q, w, \gamma)$ :

- $q \in Q$  is the current state of the automaton
- $w \in \Sigma^*$  is the remaining part of the input string
- $\blacksquare \ \gamma \in \Gamma^*$  is the current stack

For all 
$$q, q' \in Q$$
,  $a \in \Sigma \cup \{\varepsilon\}$ ,  $w \in \Sigma^*$ ,  $\alpha, \beta, \gamma \in \Gamma^*$ :

$$(q, aw, \gamma \alpha) \vdash (q', w, \beta \alpha) \text{ iff } \langle q', \beta \rangle \in \delta(q, a, \gamma)$$

 $\vdash^*$  is the reflexive transitive closure of  $\vdash$ 

## PDA: Definition (4)

There are two alternatives for the definition of the language accepted by a PDA  $M = \langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle$ :

#### Language of an PDA

The language accepted by M with a final state is

 $L(M) := \{ w \, | \, (q_0, w, Z_0) \vdash^* (q_f, \varepsilon, \gamma) \text{ for a } q_f \in F \text{ and a } \gamma \in \Gamma^* \}$ 

• The language accepted by M with an empty stack is

$$N(M) := \{ w \mid (q_0, w, Z_0) \vdash^* (q, \varepsilon, \varepsilon) \text{ for a } q \in Q \}$$

The two modes of acceptance are equivalent, i.e., for each language *L* there is a PDA  $M_1$  with  $L = L(M_1)$  iff there is a PDA  $M_2$  with  $L = N(M_2)$ .

## PDA: Definition (5)

### Example

PDA 
$$M_1$$
 for  $L(M_1) = \{wcw^R \mid w \in \{a, b\}^*\}$   

$$M_1 = \langle Q, \Sigma, \Gamma, \delta, q_0, \#, F \rangle$$

$$Q = \{q_0, q_1, q_2\}$$

$$\Sigma = \{a, b, c\}$$

$$\Gamma = \{\#, A, B\}$$

$$F = \{q_2\}.$$
Transitions:  

$$\delta(q_0, a, \varepsilon) = \{\langle q_0, A \rangle\}$$

$$\delta(q_0, b, \varepsilon) = \{\langle q_0, B \rangle\}$$

$$\delta(q_0, c, \varepsilon) = \{\langle q_1, \varepsilon \rangle\}$$

 $\delta(q_1, b, B) = \{ \langle q_1, \varepsilon \rangle \}$ 

 $\delta(q_1,\varepsilon,\#) = \{\langle q_2,\#\rangle\}$ 

## PDA: Definition (6)

δ

### Example

PDA 
$$M_2$$
 for  $N(M_2) = \{wcw^R \mid w \in \{a, b\}^*\}$   
•  $M_2 = \langle Q, \Sigma, \Gamma, \delta, q_0, \#, F \rangle$   
•  $Q = \{q_0, q_1\}$   
•  $\Sigma = \{a, b, c\}$   
•  $\Gamma = \{\#, A, B\}$   
•  $F = \emptyset$ .  
• Transitions:  
 $\delta(q_0, a, \varepsilon) = \{\langle q_0, A \rangle\}$   $\delta(q_0, b, z)$ 

$$\begin{aligned} \delta(q_0, a, \varepsilon) &= \{ \langle q_0, A \rangle \} & \delta(q_0, b, \varepsilon) &= \{ \langle q_0, B \rangle \} \\ \delta(q_0, c, \varepsilon) &= \{ \langle q_1, \varepsilon \rangle \} & \delta(q_1, a, A) &= \{ \langle q_1, \varepsilon \rangle \} \\ \delta(q_1, b, B) &= \{ \langle q_1, \varepsilon \rangle \} & \delta(q_1, \varepsilon, \#) &= \{ \langle q_1, \varepsilon \rangle \} \end{aligned}$$

# PDA: Definition (7)

#### Deterministic PDA

A PDA  $M = \langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle$  is a **deterministic PDA** (DPDA) iff

for all 
$$q \in Q, Z \in \Gamma$$
,  $a \in \Sigma \cup \{\varepsilon\}$ :  $|\delta(q, a, Z)| \le 1$ 

and

• for all 
$$q \in Q, Z \in \Gamma$$
: if  $\delta(q, \varepsilon, Z) \neq \emptyset$ , then  $\delta(q, a, Z) = \emptyset$  for all  $a \in \Sigma$ 

Examples for DPDA:  $M_1$  and  $M_2$  from the previous slides.

The class of languages accepted by DPDAs is smaller than the class accepted by (non-deterministic) PDAs.

Example of a language that requires a non-determinstic PDA:

$$\{ww^R \mid w \in \{a, b\}^*\}$$

For each CFL *L*, there is a PDA *M* with L = N(M):

- Assume that  $\varepsilon \notin L$
- L = L(G) for a CFG  $G = \langle N, T, P, S \rangle$  in GNF
- $M = \langle \{q\}, T, N, \delta, q, S, \emptyset \rangle \text{ with } \langle q, \gamma \rangle \in \delta(q, a, A) \text{ iff } A \to a\gamma \in P$
- The automaton simulates leftmost derivations in *G*

# PDA and CFG (2)

Two other possibilities to construct a PDA for a CFG  $\langle N, T, P, S \rangle$ :

Top-down, LL (no left-recursion allowed in CFG) start with stack # and  $q_0$  $\delta(q_0,\varepsilon,\#) = \{\langle q_1,S\#\rangle\}$  $\langle q_1, \alpha \rangle \in \delta(q_1, \varepsilon, A) \qquad \forall A \to \alpha \in P$  $\langle q_1, \varepsilon \rangle \in \delta(q_1, a, a) \qquad \forall a \in T$  $\delta(q_1,\varepsilon,\#) = \{\langle q_F,\varepsilon \rangle\}$ Creates a leftmost derivation Bottom-up, LR (no loops  $A \stackrel{+}{\Rightarrow} A$  allowed in CFG) start with stack # and  $q_0$  $\langle q_0, aZ \rangle \in \delta(q_0, a, Z) \qquad \forall a \in T, Z \in N \cup T \cup \{\#\}$  $\langle q_0, A \rangle \in \delta(q_0, \varepsilon, \alpha^R) \qquad \forall A \to \alpha \in P$  $(\alpha^R \text{ denotes RHS of production } A \rightarrow \alpha \text{ in reverse order})$  $\langle q_1, \varepsilon \rangle \in \delta(q_0, \varepsilon, S)$  $\langle q_F, \varepsilon \rangle \in \delta(q_1, \varepsilon, \#)$ Creates a rightmost derivation (in reverse order)

### PDA and CFG (3)

For each PDA *M* with L = N(M): *L* is a context-free language.

Construction of equivalent CFG for given PDA  $M = \langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle$ :

- Terminals:  $\Sigma$
- Nonterminals: *S* and all  $[q_1, Z, q_2]$  with  $q_1, q_2 \in Q, Z \in \Gamma$
- Start symbol: *S*
- Productions:

$$\begin{array}{l} \bullet S \rightarrow [q_0, Z_0, q] \text{ for every } q \in Q \text{ and} \\ \bullet [q, A, q_{m+1}] \rightarrow a[q_1, B_1, q_2][q_2, B_2, q_3] \dots [q_m, B_m, q_{m+1}] \text{ for} \\ q, q_1, \dots, q_{m+1} \in Q, a \in \Sigma \cup \{\varepsilon\}, A, B_1, \dots, B_m \in \Gamma \text{ such that} \\ \langle q_1, B_1 \dots B_m \rangle \in \delta(q, a, A) \\ \bullet [q, A, q_1] \rightarrow a \text{ if } \langle q_1, \varepsilon \rangle \in \delta(q, a, A) \end{array}$$

It holds:  $[q_1, A, q_2] \stackrel{*}{\Rightarrow} w \text{ iff } (q_1, w, A) \vdash^* (q_2, \varepsilon, \varepsilon)$ 

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