

Mildly Context-Sensitive Grammar

Formalisms:

LCFRS Normal Forms

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Overview

1. Introduction
2. Eliminating useless rules
3. Eliminating ε -Rules
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Introduction (1)

- A *normal form* for a grammar formalism puts additional constraints on the form of the grammar while keeping the generative capacity.
- In other words, for every grammar G of a certain formalism, one can construct a weakly equivalent grammar G' of the same formalism that satisfies additional normal form constraints.
- Example: For CFGs we know that we can construct equivalent ε -free CFGs, equivalent CFGs in Chomsky Normal Form and equivalent CFGs in Greibach Normal Form.
- Normal Forms are useful since they facilitate proofs of properties of the grammar formalism.

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Eliminating useless rules (1)

[Boullier, 1998] shows a range of useful properties of simple RCG that can help to make formal proofs and parsing easier.

Boullier defines clauses that cannot be used in derivations $S(\langle 0, n \rangle) \xrightarrow{*} \varepsilon$ for any $w \in T^*$ as *useless*.

Proposition 1 *For each simple k -RCG G , there exists an equivalent simple k' -RCG G' with $k' \leq k$ that does not contain useless rules.*

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Eliminating useless rules (2)

The removal of the useless rules can be done in the same way as in the CFG case [Hopcroft and Ullman, 1979]:

1. All rules need to be eliminated that cannot lead to a terminal sequence.

This can be done recursively: Starting from the terminating rules and following the rules from right to left, the set of all non-terminals leading to terminals can be computed recursively.

Eliminating useless rules (3)

1. (continued)

We can characterize this set N_T with the following deduction rules:

$$\frac{}{[A]} A(\vec{\alpha}) \rightarrow \varepsilon \in P$$

$$\frac{[A_1], \dots, [A_m]}{[A]} A(\vec{\alpha}) \rightarrow A_1(\vec{\alpha}_1) \dots A_m(\vec{\alpha}_m) \in P$$

All rules that contain non-terminals in their right-hand side that are not in this set are eliminated.

Eliminating useless rules (4)

2. Then the unreachable rules need to be eliminated.

This is done starting from all S -rules and moving from left-hand sides to right-hand sides. If the right-hand side contains a predicate A , then all A -rules are reachable and so on. Each time, the rules for the predicates in a right-hand side are added.

We can characterize the set N_S of non-terminals reachable from S with the following deduction rules:

$$\frac{}{[S]} \quad \frac{[A]}{[A_1], \dots, [A_m]} A(\vec{\alpha}) \rightarrow A_1(\vec{\alpha}_1) \dots A_m(\vec{\alpha}_m) \in P$$

Rules whose left-hand side predicate is not in this set are eliminated.

Eliminating ε -rules (1)

[Boullier, 1998, Seki et al., 1991] show that the elimination of ε -rules is possible in a way similar to CFG. We define that a rule is an ε -rule if one of the arguments of the left-hand side is the empty string ε .

Definition 1 A simple RCG is ε -free if it either contains no ε -rules or there is exactly one rule $S(\varepsilon) \rightarrow \varepsilon$ and S does not appear in any of the right-hand sides of the rules in the grammar.

Proposition 2 For every simple k -RCG G there exists an equivalent ε -free simple k' -RCG G' with $k' \leq k$.

Eliminating ε -rules (2)

- First, we have to compute for all predicates A , all possibilities to have empty ranges among the components of the yields.
- For this, we introduce vectors $\vec{v} \in \{0, 1\}^{dim(A)}$ and we generate a set N_ε of pairs (A, \vec{v}) where \vec{v} signifies that it is possible for A to have a tuple τ in its yield with $\tau(i) = \varepsilon$ if $\vec{v}(i) = 0$ and $\tau(i) \neq \varepsilon$ if $\vec{v}(i) \neq 0$.

Example:

$$S(XY) \rightarrow A(X, Y), A(a, \varepsilon) \rightarrow \varepsilon, A(\varepsilon, a) \rightarrow \varepsilon, A(a, b) \rightarrow \varepsilon$$

Set of pairs characterizing possibilities for ε -components:

$$N_\varepsilon = \{(S, 1), (A, 10), (A, 01), (A, 11)\}$$

Eliminating ε -rules (3)

The set N_ε is constructed recursively:

1. $N_\varepsilon = \emptyset$.
2. For every rule $A(x_1, \dots, x_{dim(A)}) \rightarrow \varepsilon$, add (A, \vec{v}) to N_ε with for all $1 \leq i \leq dim(A)$: $\vec{v}(i) = 0$ if $x_i = \varepsilon$, else $\vec{v}(i) = 1$.
3. Repeat until N_ε does not change any more:

For every rule $A(x_1, \dots, x_{dim(A)}) \rightarrow A_1(\alpha_1) \dots A_k(\alpha_k)$ and all $(A_1, \vec{v}_1), \dots, (A_k, \vec{v}_k) \in N_\varepsilon$:

Calculate a vector $(x'_1, \dots, x'_{dim(A)})$ from $(x_1, \dots, x_{dim(A)})$ by replacing every variable that is the j th variable of A_m in the right-hand side such that $\vec{v}_m(j) = 0$ with ε .

Then add (A, \vec{v}) to N_ε with for all $1 \leq i \leq dim(A)$: $\vec{v}(i) = 0$ if $x'_i = \varepsilon$, else $\vec{v}(i) = 1$.

Eliminating ε -rules (4)

Now that we have the set N_ε we can obtain reduced rules from the ones in the grammar where ε -arguments are left out.

Example:

$$S(XY) \rightarrow A(X, Y), A(a, \varepsilon) \rightarrow \varepsilon, A(\varepsilon, a) \rightarrow \varepsilon, A(a, b) \rightarrow \varepsilon$$

$$N_\varepsilon = \{(S, 1), (A, 10), (A, 01), (A, 11)\}$$

Rules after ε -elimination ((A, \vec{v}) is written $A^{\vec{v}}$):

$$S'(X) \rightarrow S^1(X), \quad (S' \text{ takes care of the case of } \varepsilon \in L(G))$$

$$S^1(X) \rightarrow A^{10}(X), A^{10}(a) \rightarrow \varepsilon,$$

$$S^1(X) \rightarrow A^{01}(X), A^{01}(b) \rightarrow \varepsilon,$$

$$S^1(XY) \rightarrow A^{11}(X, Y), A^{11}(a, b) \rightarrow \varepsilon$$

Eliminating ε -rules (5)

To obtain the new rules P_ε , we proceed as follows:

1. $P_\varepsilon = \emptyset$
2. We pick a new start symbol $S' \notin N_\varepsilon$.
If $\varepsilon \in L(G)$, we add $S'(\varepsilon) \rightarrow \varepsilon$ to P_ε .
If $S^1 \in N_\varepsilon$, we add $S'(X) \rightarrow S^1(X)$ to P_ε .
3. For every rule $A(\alpha) \rightarrow A_1(\vec{x}_1) \dots A_k(\vec{x}_k) \in P$: add all ε -reductions of this rule to P_ε .

Eliminating ε -rules (6)

The ε -reductions of $A(\alpha) \rightarrow A_1(\vec{x}_1) \dots A_k(\vec{x}_k)$ are obtained as follows:

For all combinations of $\vec{t}_1, \dots, \vec{t}_k$ such that $A_i^{\vec{t}_i} \in N_\varepsilon$ for $1 \leq i \leq k$:

- (i) For all $i, 1 \leq i \leq k$: replace A_i in the rhs with $A_i^{\vec{t}_i}$ and for all $j, 1 \leq j \leq \dim(A_i)$: if $\vec{t}_i(j) = 0$, then remove the j th component of $A_i^{\vec{t}_i}$ from the rhs and delete the variable $\vec{x}_i(j)$ in the lhs.
- (ii) Let $\vec{t} \in \{0, 1\}^{\dim(A)}$ be the vector with $\vec{t}(i) = 0$ iff the i th component of A is empty in the rule obtained from (i). Remove all ε -components in the lhs and replace A with $A^{\vec{t}}$.

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Ordered Simple RCG (1)

In general, in MCFG/LCFRS/simple RCG, when using a rule in a derivation, the order of the components of its lhs in the input is not necessarily the order of the components in the rule.

Example:

$S(XY) \rightarrow A(X, Y), A(aXb, cYd) \rightarrow A(Y, X), A(e, f) \rightarrow \varepsilon.$

String language:

$\{(ac)^n e (db)^n (ca)^n f (bd)^n \mid n \geq 0\}$
 $\cup \{(ac)^n a f b (db)^n (ca)^n c e d (bd)^n \mid n \geq 0\}$

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Ordered Simple RCG (2)

Definition 2 (Ordered simple RCG) A simple RCG is ordered if for every rule $A(\vec{\alpha}) \rightarrow A_1(\vec{\alpha}_1) \dots A_k(\vec{\alpha}_k)$ and every $A_i(\vec{\alpha}_i) = A_i(Y_1, \dots, Y_{\dim(A_i)})$ ($1 \leq i \leq k$), the order of the components of $\vec{\alpha}_i$ in $\vec{\alpha}$ is $Y_1, \dots, Y_{\dim(A_i)}$.

Proposition 3 For every simple k -RCG G there exists an equivalent ordered simple k -RCG G' .

[Michaelis, 2001, Kracht, 2003, Kallmeyer, 2010]

In LCFRS terminology, this property is called *monotone* while in MCFG terminology, it is called *non-permuting*.

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Ordered Simple RCG (3)

Idea of the transformation:

- We check for every rule whether the component order in one of the right-hand side predicates A does not correspond to the one in the left-hand side.
- If so, we add a new predicate that differs from A only with respect to the order of the components. We replace A in the rule with the new predicate with reordered components.
- Furthermore, we add a copy of every A -rule with A replaced in the left-hand side by the new predicate and reordering of the components.

We notate the permutations of components as vectors where the i th element is the image of i . For a predicate A , id is the vector $\langle 1, 2, \dots, \dim(A) \rangle$.

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Ordered Simple RCG (4)

Transformation into an ordered simple RCG:

$P' := P$ with all predicates A replaced with A^{id} ;

$N' := \{A^{id} \mid A \in N\}$;

repeat until P' does not change any more:

for all $r = A^p(\vec{\alpha}) \rightarrow A_1^{p_1}(\vec{\alpha}_1) \dots A_k^{p_k}(\vec{\alpha}_k)$ in P' :

for all i , $1 \leq i \leq k$:

if $A_i^{p_i}(\vec{\alpha}_i) = A_i^{p_i}(Y_1, \dots, Y_{dim(A_i)})$ and the order of the
 $Y_1, \dots, Y_{dim(A_i)}$ in $\vec{\alpha}_i$ is $p(Y_1, \dots, Y_{dim(A_i)})$

where p is not the identity

then replace $A_i^{p_i}(\vec{\alpha}_i)$ in r with $A_i^{p_i \circ p}(p(\vec{\alpha}_i))$

if $A_i^{p_i \circ p} \notin N'$ then add $A_i^{p_i \circ p}$ to N' and

for every $A_i^{p_i}$ -rule $A_i^{p_i}(\vec{\gamma}) \rightarrow \Gamma \in P'$:

add $A_i^{p_i \circ p}(p(\vec{\gamma})) \rightarrow \Gamma$ to P'

Ordered Simple RCG (5)

Consider again our example

$P' = \{S(XY) \rightarrow A(X, Y), A(aXb, cYd) \rightarrow A(Y, X), A(e, f) \rightarrow \varepsilon\}$.

- Problematic rule: $A^{(1,2)}(aXb, cYd) \rightarrow A^{(1,2)}(Y, X)$
- Introduce new non-terminal $A^{(2,1)}$ where $\langle 2, 1 \rangle$ is the permutation that switches the two arguments.
Replace $A^{(1,2)}(aXb, cYd) \rightarrow A^{(1,2)}(Y, X)$ with
 $A^{(1,2)}(aXb, cYd) \rightarrow A^{(2,1)}(X, Y)$.
- Add $A^{(2,1)}(f, e) \rightarrow \varepsilon$ and $A^{(2,1)}(cYd, aXb) \rightarrow A^{(2,1)}(X, Y)$.
- Now, $A^{(2,1)}(cYd, aXb) \rightarrow A^{(2,1)}(X, Y)$ is problematic.
 $\langle 2, 1 \rangle \circ \langle 2, 1 \rangle = \langle 1, 2 \rangle$, therefore we replace this rule with
 $A^{(2,1)}(cYd, aXb) \rightarrow A^{(1,2)}(Y, X)$. $A^{(1,2)}$ is no new non-terminal, so no further rules are added.

Ordered Simple RCG (6)

Result:

$$S^{(1)}(XY) \rightarrow A^{(1,2)}(X, Y) \quad A^{(1,2)}(e, f) \rightarrow \varepsilon$$

$$A^{(1,2)}(aXb, cYd) \rightarrow A^{(2,1)}(X, Y) \quad A^{(2,1)}(f, e) \rightarrow \varepsilon$$

$$A^{(2,1)}(cYd, aXb) \rightarrow A^{(1,2)}(Y, X)$$

Note that in general, this transformation algorithm is exponential in the size of the original grammar.

Binarization (1)

In LCFRS terminology, the length of the right-hand side of a production is called its *rank*. The *rank* of an LCFRS is given by the maximal rank of its productions.

Proposition 4 *For every simple RCG/LCFRS G there exists an equivalent simple RCG/LCFRS G' that is of rank 2.*

Unfortunately, the fan-out of G' might be higher than the fan-out of G .

The transformation can be performed similarly to the CNF transformation for CFG [Hopcroft and Ullman, 1979, Grune and Jacobs, 2008].

Binarization (2)

Example:

$$S(XYZUVW) \rightarrow A(X,U)B(Y,V)C(Z,W)$$

$$A(aX, aY) \rightarrow A(X, Y) \quad A(a, a) \rightarrow \varepsilon$$

$$B(bX, bY) \rightarrow B(X, Y) \quad B(b, b) \rightarrow \varepsilon$$

$$C(cX, cY) \rightarrow C(X, Y) \quad C(c, c) \rightarrow \varepsilon$$

Equivalent binarized grammar:

$$S(XPUQ) \rightarrow A(X,U)C_1(P, Q) \quad C_1(YZ, VW) \rightarrow B(Y,V)C(Z, W)$$

$$A(aX, aY) \rightarrow A(X, Y) \quad A(a, a) \rightarrow \varepsilon$$

$$B(bX, bY) \rightarrow B(X, Y) \quad B(b, b) \rightarrow \varepsilon$$

$$C(cX, cY) \rightarrow C(X, Y) \quad C(c, c) \rightarrow \varepsilon$$

Binarization (3)

We define the *reduction of a vector* $\vec{\alpha}_1 \in [(T \cup V)^*]^{k_1}$ by a vector $\vec{x} \in (V^*)^{k_2}$ where all variables in \vec{x} occur in $\vec{\alpha}_1$ as follows:

Take all variables from $\vec{\alpha}_1$ (in their order) that are not in \vec{x} while starting a new component in the resulting vector whenever an element is, in $\vec{\alpha}_1$, the first element of a component or preceded by a variable from \vec{x} or a terminal.

Examples:

1. $\langle aX_1, X_2, bX_3 \rangle$ reduced with $\langle X_2 \rangle$ yields $\langle X_1, X_3 \rangle$.
2. $\langle aX_1X_2bX_3 \rangle$ reduced with $\langle X_2 \rangle$ yields $\langle X_1, X_3 \rangle$ as well.

Binarization (4)

Transformation into a simple RCG of rank 2:

for all $r = A(\vec{\alpha}) \rightarrow A_0(\vec{\alpha}_0) \dots A_m(\vec{\alpha}_m)$ in P with $m > 1$:

remove r from P and pick new non-terminals C_1, \dots, C_{m-1}

$R := \emptyset$

add the rule $A(\vec{\alpha}) \rightarrow A_0(\vec{\alpha}_0)C_1(\vec{\gamma}_1)$ to R where $\vec{\gamma}_1$

is obtained by reducing $\vec{\alpha}$ with $\vec{\alpha}_0$

for all i , $1 \leq i \leq m-2$:

add the rule $C_i(\vec{\gamma}_i) \rightarrow A_i(\vec{\alpha}_i)C_{i+1}(\vec{\gamma}_{i+1})$ to R where $\vec{\gamma}_{i+1}$

is obtained by reducing $\vec{\gamma}_i$ with $\vec{\alpha}_i$

add the rule $C_{m-1}(\vec{\gamma}_{m-2}) \rightarrow A_{m-1}(\vec{\alpha}_{m-1})A_m(\vec{\alpha}_m)$ to R

for every rule $r' \in R$

replace rhs arguments of length > 1 with new variables

(in both sides) and add the result to P

Binarization (5)

In our example, for the rule

$S(XYZUVW) \rightarrow A(X,U)B(Y,V)C(Z,W)$, we obtain

$$R = \left\{ \begin{array}{l} S(XYZUVW) \rightarrow A(X,U)C_1(YZ, VW), \\ C_1(YZ, VW) \rightarrow B(Y,V)C(Z, W) \end{array} \right\}$$

Collapsing sequences of adjacent variables in the rhs leads to the two rules

$$S(XPUQ) \rightarrow A(X,U)C_1(P, Q), \quad C_1(YZ, VW) \rightarrow B(Y,V)C(Z, W)$$

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