



Language modeling with tree-adjoining grammars

Grammar implementation with XMG

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^aand some slides by Timm Lichte

Outline

Overview

Intuition

eXtensible Metagrammar (XMG)

Principles / colors

Summary

Last sessions

Mon: Motivation and the basic TAG

Tue: Linguistic applications and using LTAG: syntax

Wed: Linguistic applications and using LTAG: semantics

The following sessions

Wed: Introduction to grammar engineering and XMG

Thu: Grammar implementation with XMG

Fri: Parsing TAG

Overview

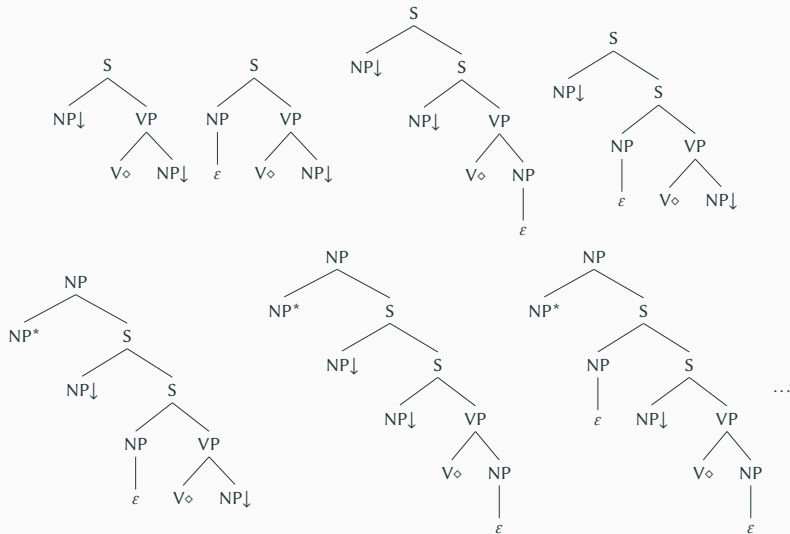
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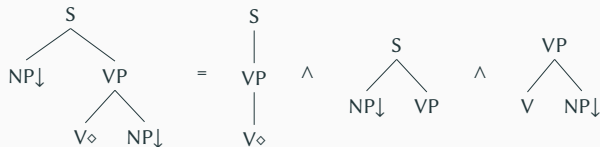
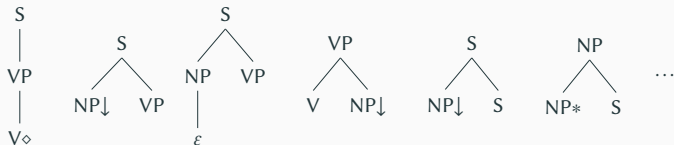
Summary

The problem: large (but highly redundant) families

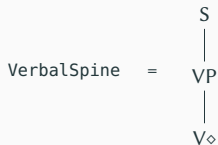


- Idea: describe smaller units to capture redundancies
- Tree fragments: reusable abstractions based on linguistic (or not) generalizations
- Once the fragments are defined, the trees are created by assembling the fragments

Abstractions - Tree fragments

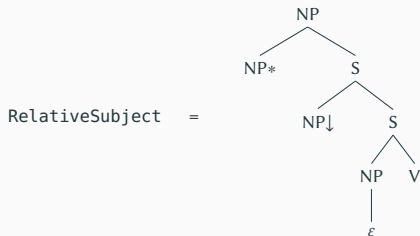
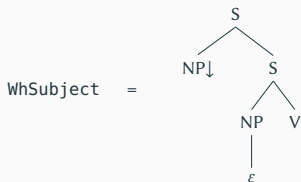
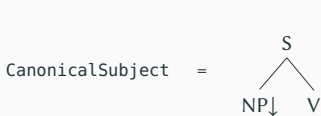


Named abstractions - Classes



SimpleTransitive = VerbalSpine \wedge CanonicalSubject \wedge CanonicalObject

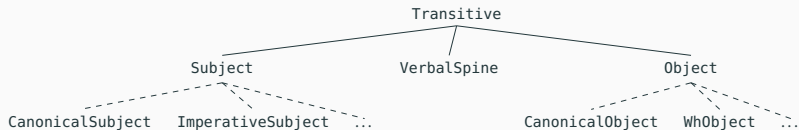
Expressing alternatives - Disjunction

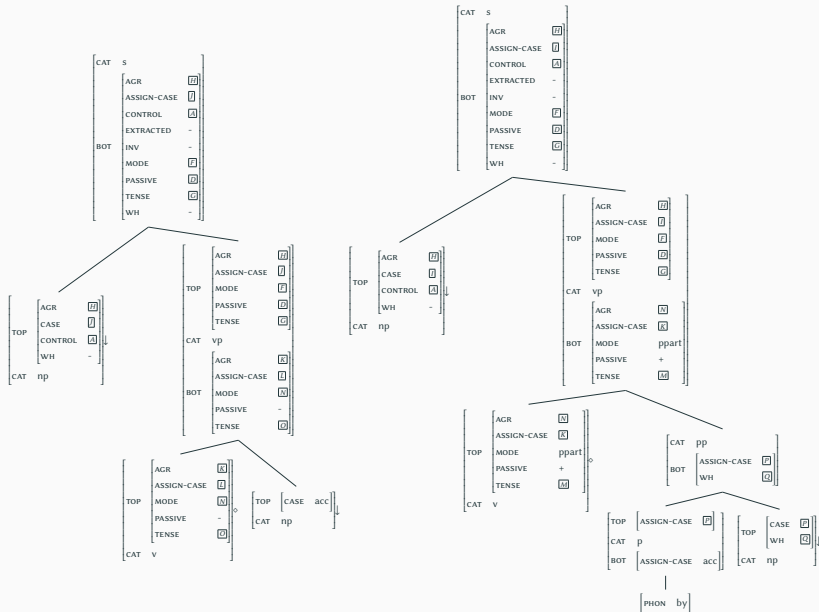


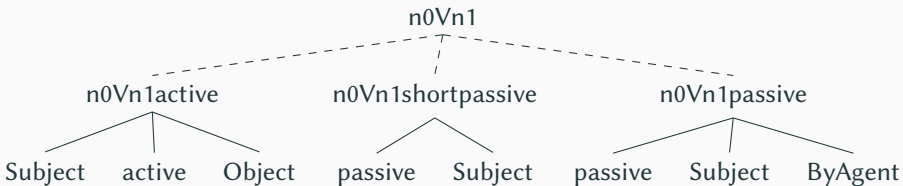
Subject = CanonicalSubject ∨ ImperativeSubject ∨ WhSubject
∨ RelativeSubject ∨ ...

Building complex class hierarchies - Families

Transitive = Subject \wedge VerbalSpine \wedge Object







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eXtensible Metagrammar (XMG): Background

- Developed at LORIA, Nancy, LIFO, Orléans and HHU, Düsseldorf.^[4,7]
- Description language based on logic and constraints
- All information at <https://xmg.phil.hhu.de>

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Why “eXtensible” ?

- Highly modularized^[6]
- Dimensions with dedicated description languages and compilers
(**<syn>**, **<sem>**, **<frame>**, **<morph>**, ...)
- Interface using shared variables

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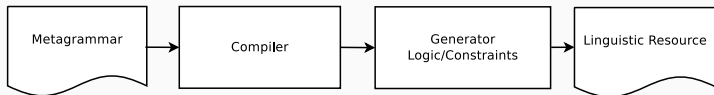
Some existing implementations using XMG:

- French: FrenchTAG^[3]
- English: XTAG with XMG^[1]
- German: GerTT^[5]
- Arabic: ArabTAG^[2]

How does it work?

XMG processing steps are as follow:

- The metagrammar is compiled: metagrammatical descriptions are translated into executable code
- The generated code is executed: accumulation of descriptions into the dimensions
- Descriptions are solved: every dimension comes with a dedicated solver
- Models are converted into the output language (XML)



Installing XMG 2

Three options, provided by the documentation:

<https://github.com/spetitjean/XMG-2/wiki>

- Follow the steps (Ubuntu), or
- Install VirtualBox and get the XMG image
- Use the online compiler(s): <https://xmg.phil.hhu.de/index.php/upload/workbench>

XMG descriptions:

- Associate a content to an identifier (abstraction)
- Describe structures inside dimensions, with dedicated languages
- Use other abstractions (classes)
- Combine contents in a disjunctive or a conjunctive way

$Class := Name \rightarrow Content$

$Content := \langle Dimension \rangle \{ Description \} \mid Name \mid$
 $Content \vee Content \mid Content \wedge Content$

Describing trees

The <syn> dimension

- Declaring nodes: keyword **node**, optional node variable, optional features and properties
node ?S [cat=s]
- Expressing constraints between nodes: dominance operators (->, ->+, ->*) and precedence operators (>>, >>+, >>*)
- Combining these statements: with logical operators (; and |)

Example:

```
1   node ?S [cat=s];  
2   node ?VP [cat=vp];  
3   node ?NP (mark=subst) [cat=n];  
4   ?S -> ?VP;  
5   ?S -> ?NP;  
6   ?NP >> ?VP
```

Alternative syntax: bracket notation

The <syn> dimension

- Declaring nodes: same as for the standard notation
- Expressing dominance and precedence constraints thanks to bracketing, and special operators for non immediate relations (... , ...+ , ... , ... , ...+)

```
1   node ?S [cat=s]{
2     node ?NP (mark=subst) [cat=np]
3     node ?VP [cat=vp]
4   }
```

Using dimensions

Contributing descriptions

- Descriptions (constraints) are accumulated into dimensions
- Every dimension is associated to a solver (sometimes identity)
- **<syn>**: a tree solver generates all minimal models

```
1 <syn>{
2     node ?S [cat=s];
3     node ?VP [cat=vp];
4     node ?NP (mark=subst) [cat=n];
5     ?S -> ?VP;
6     ?S -> ?NP;
7     ?NP >> ?VP
8 }
```

Two nodes can be unified if:

- their feature structures can be unified
- their properties can be unified (except for colors, see later)

Unification of nodes happens at two different stages:

- During the execution of the code (“explicit” unification: unification operator = or common variable name in different classes)
- After solving: some nodes may be merged to obtain a minimal model

Minimal models

A minimal model is a model of the description where:

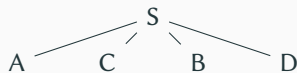
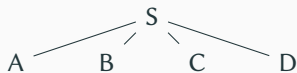
- no constraint is violated
- no additional node is created

What are the minimal models for the following sets of constraints?

- 1 **node** ?S [cat = s] ; **node** ?A [cat = a] ; **node** ?B [cat = b]
- 2 ; ?S -> ?A ; ?S -> ?B

- 1 **node** ?S [cat = s] ; **node** ?A [cat = a] ; **node** ?B [cat = b]
- 2 ; **node** ?C [cat = c] ; ?S -> ?A ; ?S -> ?B ; ?S -> ?C ; ?A >>* ?C

Which set of constraints leads to the following minimal models?



Defining abstractions

Classes allow to:

- Control the scope of variables
- Make (parametrized) abstractions

Examples (just headers):

```
1 class kicked_the_bucket
2 import nx0Vnx1[]
3 declare ?X0 ?X1
```

```
1 class nx0Vnx1
2 export ?S ?NP_Subj ?VP ?V ?NP_Obj
3 declare ?S ?NP_Subj ?VP ?V ?NP_Obj ?X0 ?X1
```

Defining abstractions

```
1 class Intransitive
2 declare ?S ?NP ?VP ?V
3 {
4   <syn>{
5     node ?S [cat=s];
6     node ?VP [cat=vp];
7     node ?V (mark=anchor) [cat=v];
8     node ?NP (mark=subst) [cat=n];
9     ?S -> ?VP; ?VP -> ?V;
10    ?S -> ?NP; ?NP >> ?VP
11  }
12 }
```

Valuation

To specify for which class models have to be computed (the axioms), the instruction **value** has to be used after the class definitions.

```
1 value Intransitive
```

Using abstractions

Classes can be used by other classes by two means:

- Importing the class in the header: all the (exported) variables are added to the scope, all the constraints from the class are added to the current set of constraints
- Calling the class in the body: variables are not added to the scope, but can be accessed with the dot operator

Calling classes has two advantages:

- alternatives are possible (disjunction)
- it allows to use parameters

Examples:

```
1 CanObj[] | RelObj[]
```

```
1 ?C = AnotherClass[?AParameter] ; ?LocalNP = ?C.?NP
```

Classes: examples (1)

```
1 class a
2 export ?A
3 declare ?A ?S
4 {
5   <syn>{
6     node ?S [cat = s];
7     node ?A [cat = a];
8     ?S -> ?A
9   }
10 }
```

```
1 class b
2 import a[]
3 declare ?B
4 {
5   <syn>{
6     node ?B [cat = b];
7     ?A -> ?B
8   }
9 }
```

Classes: examples (2)

```
1 class a
2 export ?S
3 declare ?A ?S
4 {
5   <syn>{
6     node ?S [cat = s];
7     node ?A [cat = a];
8     ?S -> ?A
9   }
10 }
```

```
1 class b
2 import a[]
3 declare ?A
4 {
5   <syn>{
6     node ?A [cat = a];
7     ?S -> ?A
8   }
9 }
```

Classes: examples (3)

```
1 class a
2 export ?S
3 declare ?A ?S
4 {
5   <syn>{
6     node ?S [cat = s];
7     node ?A [cat = a];
8     ?S -> ?A
9   }
10 }
```

```
1 class b
2 declare ?A ?Class
3 {
4   ?Class = a[];
5   <syn>{
6     node ?A [cat = a];
7     ?Class.?S -> ?A
8   }
9 }
```

Classes: examples (4)

```
1 class a
2 export ?S
3 declare ?A ?S
4 {
5   <syn>{
6     node ?S [cat = s];
7     node ?A [cat = a];
8     ?S -> ?A
9   }
10 }
```

```
1 class b
2 declare ?S ?Class
3 {
4   ?Class = a[];
5   <syn>{
6     node ?S [cat = s];
7     ?Class.?S -> ?S
8   }
9 }
```


Definition of types and constants

Everything inside the metagrammar has a type: values, feature structures, nodes, dimensions...

Four ways to define new types:

- Enumerated type: type $T = \{a, b, c, d\}$
- Structured type: type $T = [a_1:t_1, \dots, a_n:t_n]$
- Interval type: type $T = [1..3]$
- Unspecified type: type $T!$

Definition of types and constants

We can now specify the types of features and properties:

```
1  type CAT= {np, vp, s, n, v, det}
2  type MARK= {lex, anchor, subst}
3  type LABEL !
4  type PERS= [1..3]
5  type GEN = {m, f}
6  type NUM = {sg, pl}
7  type AGR = [gen:GEN, num:NUM]
8
9
10 feature cat: CAT
11 feature e: LABEL
12 feature pers: PERS
13 feature agr: AGR
14
15 property mark: MARK
```

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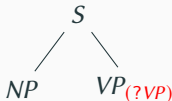
Summary

Combining tree fragments

- We know how to define tree fragments
- We have a clear idea of how they should combine
- Without additional constraints, XMG combines the fragments in all possible ways, as long as the models are minimal
- Explicitly specifying which nodes should be unified: tedious and error prone

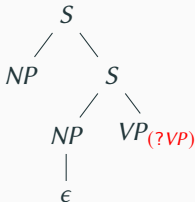
Defining a tree fragment

```
1  class CanonicalSubject
2  export VP
3  declare ?S ?NP ?VP
4  {
5    <syn>{
6      node ?S[cat = s];
7      node ?NP[cat = np];
8      node ?VP[cat = vp];
9      ?S -> ?NP;
10     ?S -> ?VP;
11     ?NP >> ?VP }
12 }
```

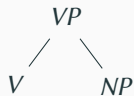
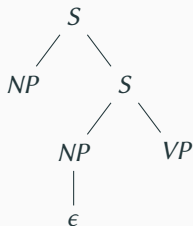
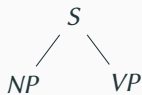


Defining a tree fragment

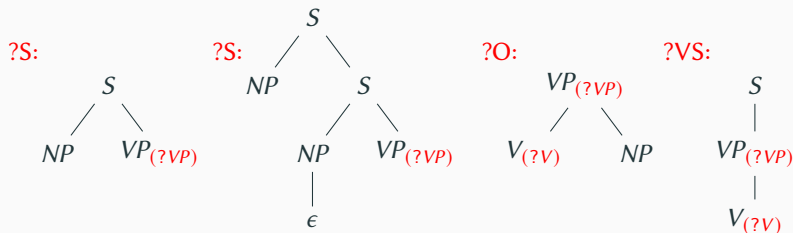
```
1  class WhSubject
2  export VP
3  declare ?S ?S1 ?NP ?NP1 ?E ?VP
4  {
5    <syn>{
6      node ?S[cat = s] ; node ?NP[cat = np] ; node ?S1 [cat = s] ;
7      node ?NP1 [cat = np] ; node ?E (mark = lex) [cat = e] ;
8      node ?VP [cat = vp] ;
9      ?S -> ?NP ; ?S -> ?S1; ?NP >> ?S1; ?S1 -> NP1;
10     ?NP1 -> ?E ; ?S1 -> ?VP; ?NP1 >> ?VP }
11 }
```



Assembling fragments



Assembling fragments



```
1 class Transitive
2 declare ?S ?O ?V
3 {
4   ?S = Subject[];
5   ?O = CanonicalObject[];
6   ?VS = VerbalSpine[];
7   ?S.?VP = ?O.?VP;
8   ?S.?VP = ?VS.?VP;
9   ?VS.?V = ?O.?V
10 }
```

- Three last lines: not satisfying
- One solution: import the classes
- New problem: handling variable names

Handling export and disjunction

```
1  class Subject
2  export VP
3  declare ?CS ?WS ?VP
4  {
5    { ?CS = CanonicalSubject[]; ?VP = ?CS.?VP }
6    |
7    { ?WS = WhSubject[]; ?VP = ?WS.?VP}
8  }
```

- Simpler and safer without the export of the ?VP node

- Variables in XMG classes: local by default
- Advantages: avoid variable name conflicts, easier maintenance
- Disadvantages: hard to express constraints which span on several classes
- Refer to variables in foreign classes: export and import or class instantiation
- Problem: disjunction makes things more complex

Describing global constraints locally

- Aim: describe global constraints locally
- Principles: solution offered by XMG
- When do we need principles, and which ones?
- Which principles are already implemented?
- How to implement more principles?

The colors principle

- Example: previous section
- Idea: a polarity system to control fragment combinations
- A color is associated to every node
- New unification rules are given by the colors
- Proposed in **Duchier2004**

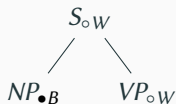
Filtering combinations with polarities

- A black node is a resource, and can be unified with white nodes
- A white node is a need, and must be unified with a black node
- A red node is saturated, and cannot be unified

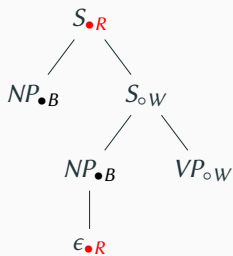
	● _B	● _R	○ _W	⊥
● _B	⊥	⊥	● _B	⊥
● _R	⊥	⊥	⊥	⊥
○ _W	● _B	⊥	○ _W	⊥
⊥	⊥	⊥	⊥	⊥

- A valid model is composed of only red and black nodes

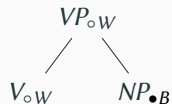
Colored tree fragments



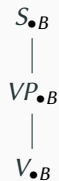
CanonicalSubject



WhSubject



CanonicalObject



VerbalSpine

Code for a colored tree fragment

```
1  use color with () dims (syn)
2  type COLOR = {red, black, white}
3  property color : COLOR
4  ...
5
6  class CanonicalSubject
7  declare ?S ?NP ?VP
8  {
9    <syn>{
10     node ?S(color=white)[cat=s];
11     node ?NP(color=black)[cat=np];
12     node ?VP(color=white)[cat=np];
13     ?S -> ?NP;
14     ?S -> ?VP;
15     ?NP >> ?VP }
16 }
```

Assembling fragments with colors

- The Transitive class does not need to do explicit unifications

```
1 class Transitive
2 {
3     Subject[]; CanonicalObject[]; VerbalSpine[]
4 }
```


Assembling fragments with colors

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```
1 class Transitive
2 {
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4 }
```

- The Subject class does not need to re-export variables

```
1 class Subject
2 {
3   CanonicalSubject[] | WhSubject[]
4 }
```

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- What is left?

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```

- What is left? The class hierarchy! Only terminal classes hold descriptions

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Summary

- A metagrammar contains descriptions of unanchored elementary trees.
- Metagrammar descriptions are declarative and multidimensional.
- Metagrammar descriptions make up an inheritance hierarchy.
- The metagrammar allows one to express and implement lexical generalizations, e.g. active-passive diathesis.

- [1] Alahverdzhieva, Katya. 2008. *XTAG using XMG. A core Tree-Adjoining Grammar for English*. University of Nancy 2 / University of Saarland Master's Thesis. <http://homepages.inf.ed.ac.uk/s0896251/pubs/msc-sb2008.pdf>.
- [2] Ben Khelil, Chérifa, Denys Duchier, Yannick Parmentier, Chiraz Zribi & Fériel Ben Fraj. 2016. ArabTAG: from a handcrafted to a semi-automatically generated TAG. In *Proceedings of the 12th international workshop on tree adjoining grammars and related formalisms (TAG+12)*, 18–26. Düsseldorf, Germany. <https://aclanthology.org/W16-3302>.
- [3] Crabbé, Benoît. 2005. *Représentation informatique de grammaires d'arbres fortement lexicalisées: Le cas de la grammaire d'arbres adjoints*. Université Nancy 2 dissertation.
- [4] Crabbé, Benoit, Denys Duchier, Claire Gardent, Joseph Le Roux & Yannick Parmentier. 2013. XMG: eXtensible MetaGrammar. *Computational Linguistics* 39(3). 1–66. <http://hal.archives-ouvertes.fr/hal-00768224/en/>.
- [5] Kallmeyer, Laura, Timm Lichte, Wolfgang Maier, Yannick Parmentier & Johannes Dellert. 2008. Developing a TT-MCTAG for German with an RCG-based parser. In European Language Resources Association (ELRA) (ed.), *Proceedings of the sixth international Conference on Language Resources and Evaluation (LREC'08)*. Marrakech, Morocco.
- [6] Petitjean, Simon. 2014. *Génération Modulaire de Grammaires Formelles*. Orléans, France: Université d'Orléans Thèse de Doctorat. <https://tel.archives-ouvertes.fr/tel-01163150/>.
- [7] Petitjean, Simon, Denys Duchier & Yannick Parmentier. 2016. XMG 2: Describing Description Languages. In *Logical aspects of computational linguistics. celebrating 20 years of lacl (1996–2016) 9th international conference, lacl 2016, nancy, france, december 5-7, 2016, proceedings 9*, 255–272.